

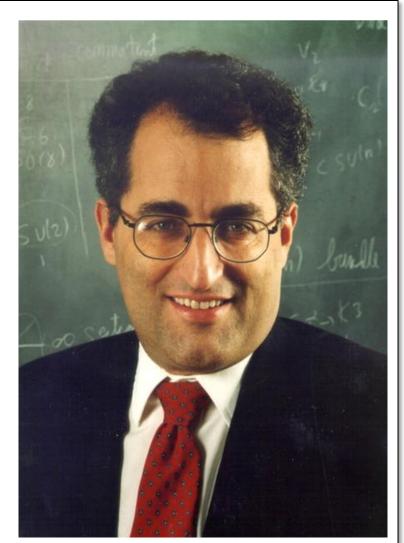
Chapter 5: Integration

LECTURE	Τορις
19	ANTIDERIVATIVES
20	INTEGRATION: AREA AND DISTANCE
21	The Definite Integral
22	Fundamental Theorem of Calculus

Calculus Inspiration

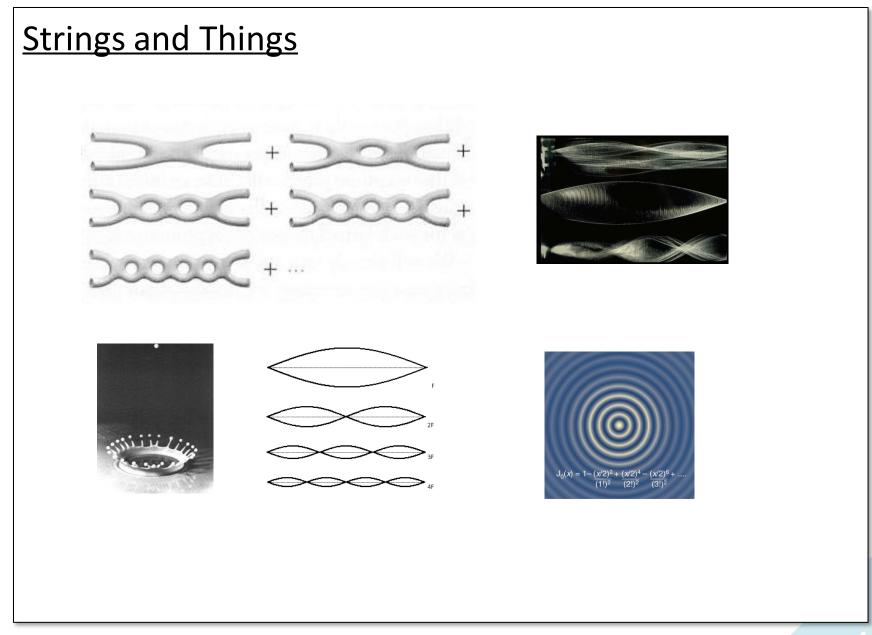
Edward Witten PhD. Princeton

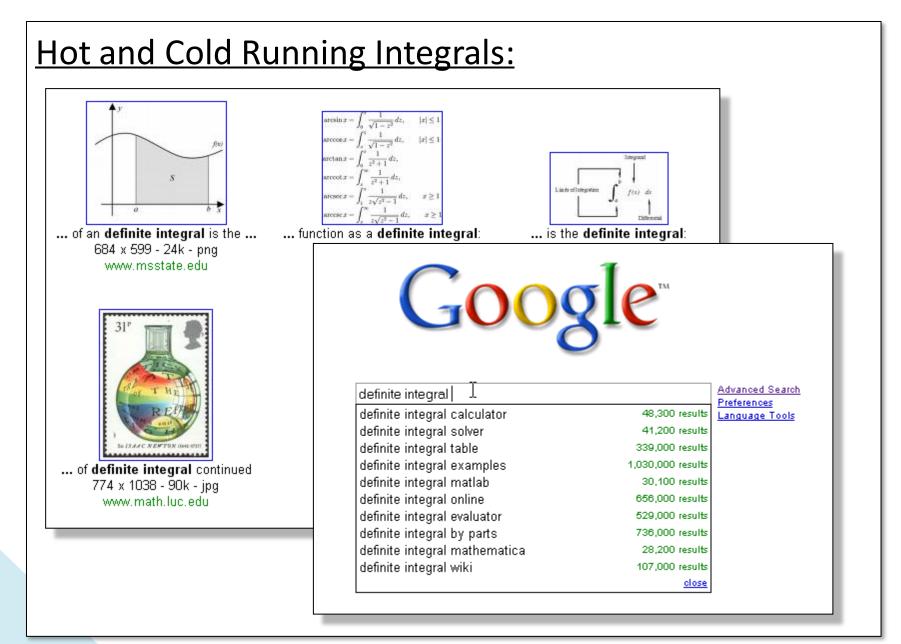
- M Theory
- String Theory
- Quantum Theory
- Fields Medal (1990)
- Poincare Prize (2006)
- Crafoord Prize (2008)
- A Living Einstein

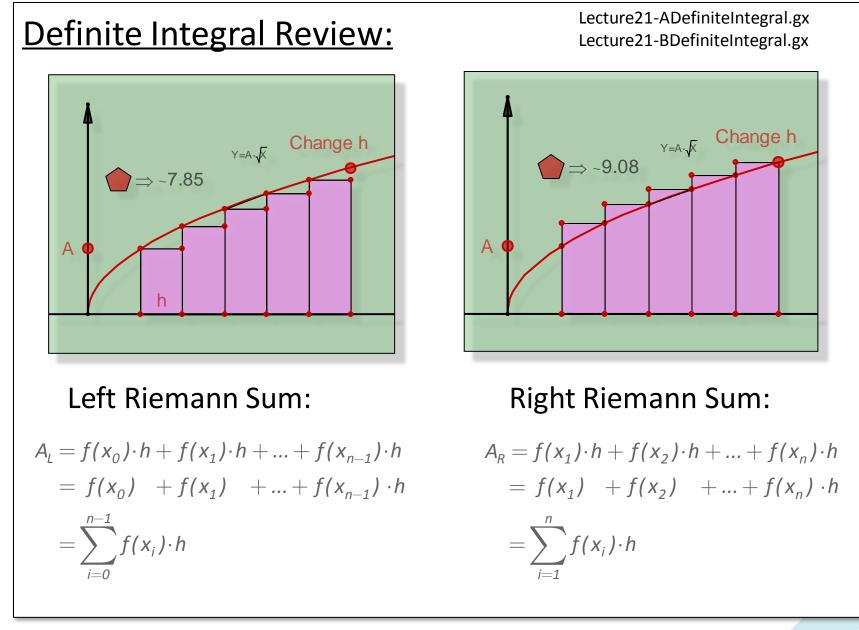


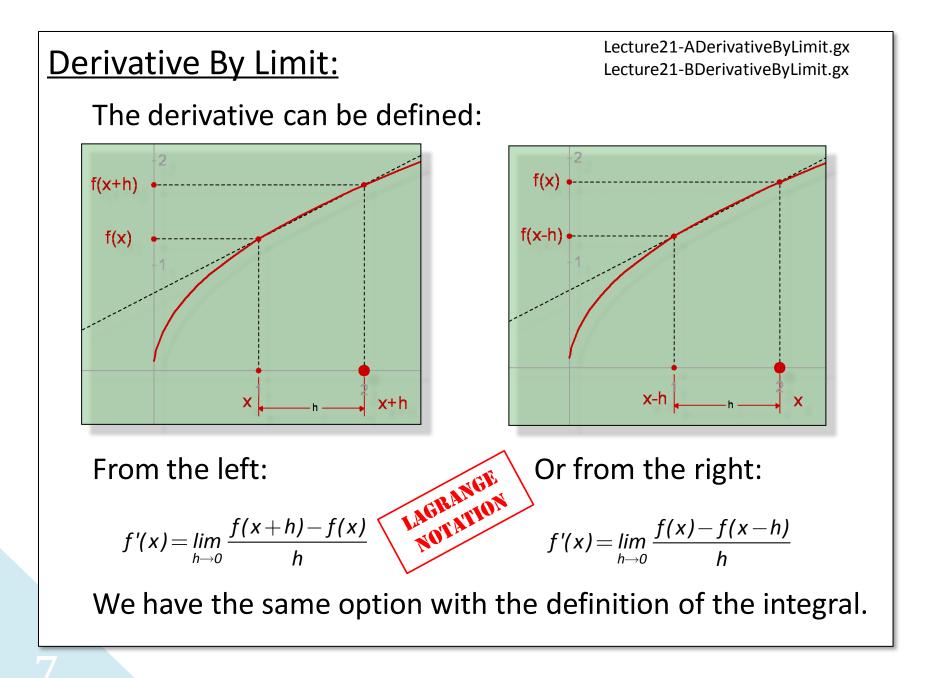
Courtesy: Institute for Advanced Study

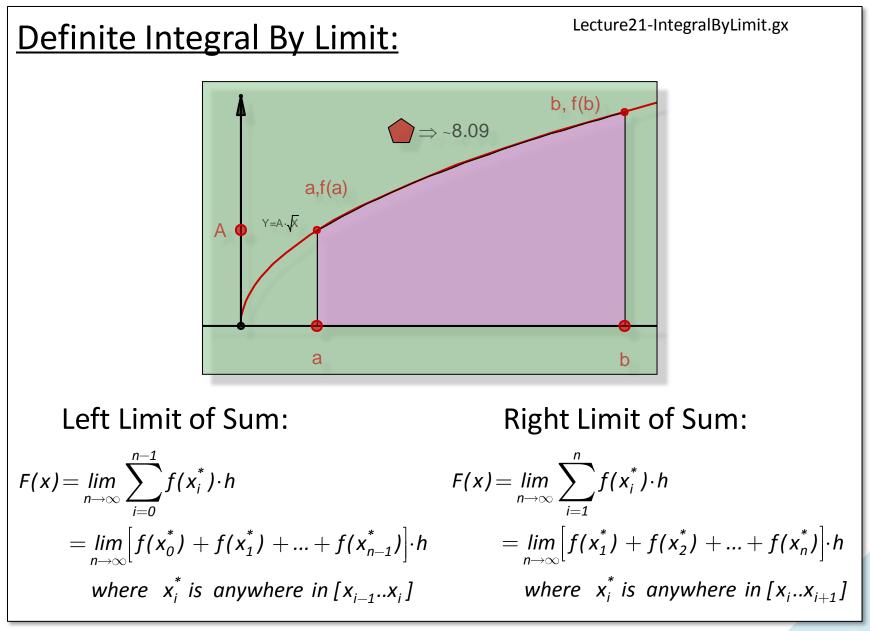
Genealogy is David Gross \rightarrow Geoffrey Chew \rightarrow Enrico Fermi

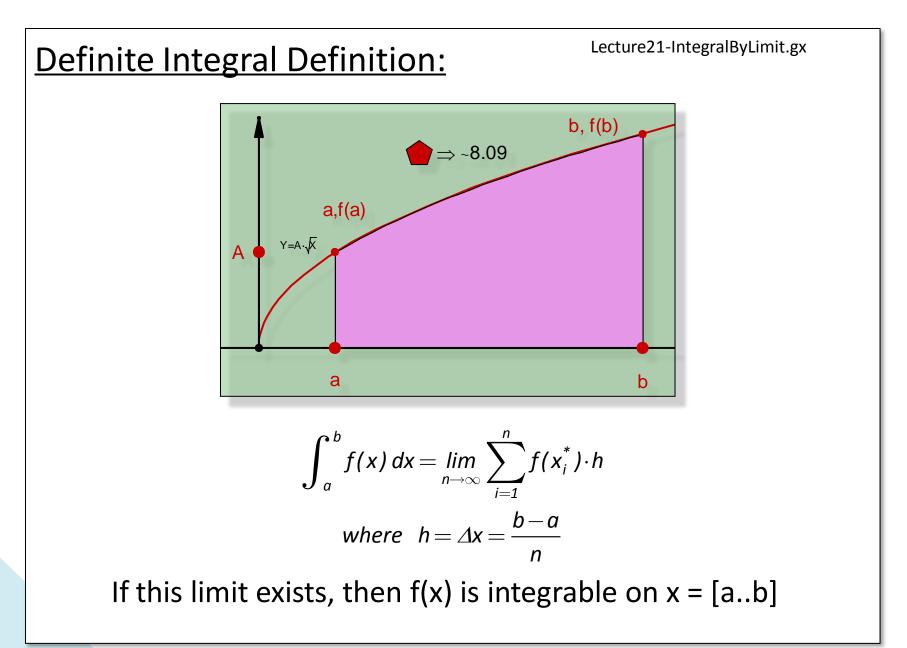


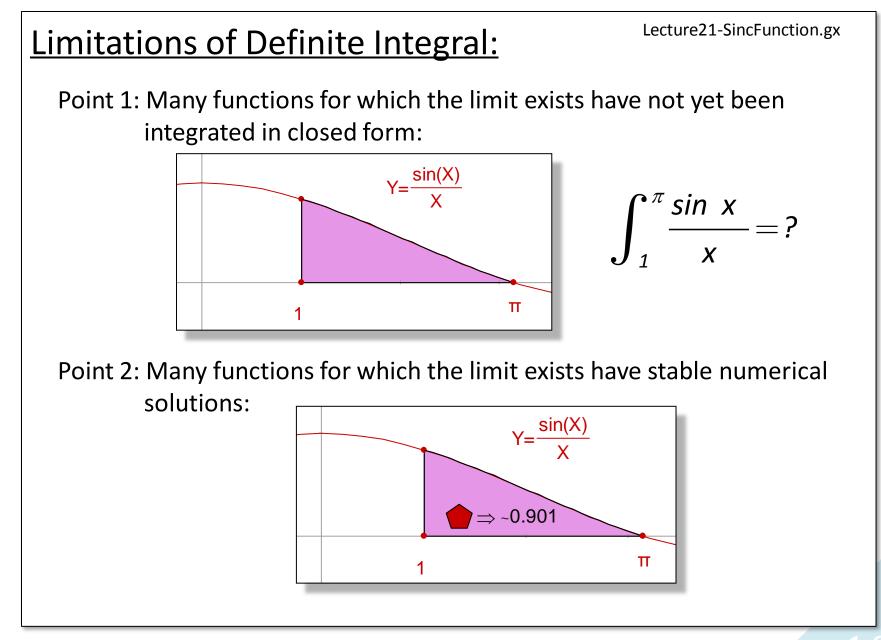








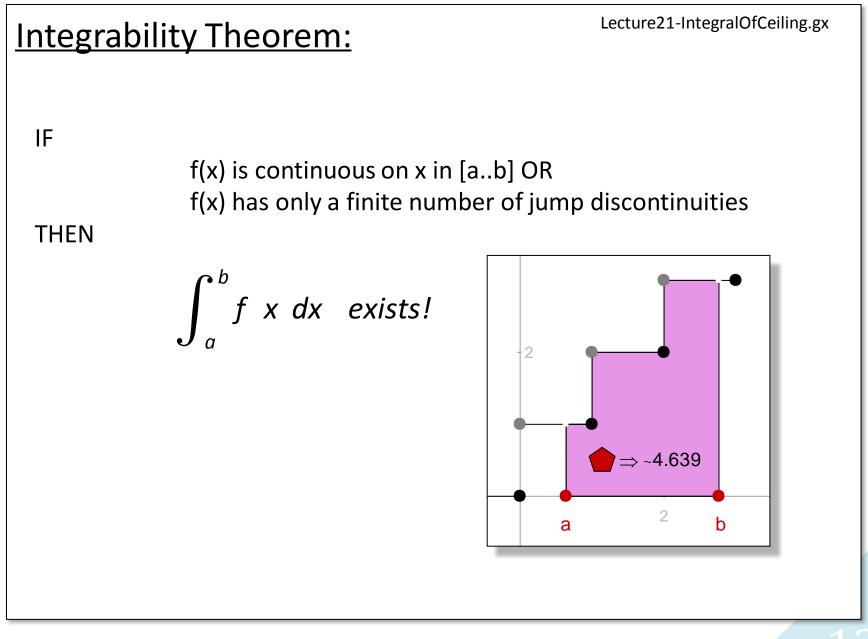




Lecture 21 – The Definite Integral

Precise Meaning of Definite Integral Limit:
For every number
$$\varepsilon > 0$$
, there is an integer N such that:

$$\left| \int_{a}^{b} f x \, dx - \lim_{n \to \infty} \sum_{i=1}^{n} f(x_{i}^{*}) \cdot \Delta x \right| < \varepsilon$$
For every integer n > N and for every choice of x_{i}^{*} in $[x_{i-1}...x_{i}]$.



<u>First Choice for x_i^* :</u>

If we choose $x_i^* = x_i$ then

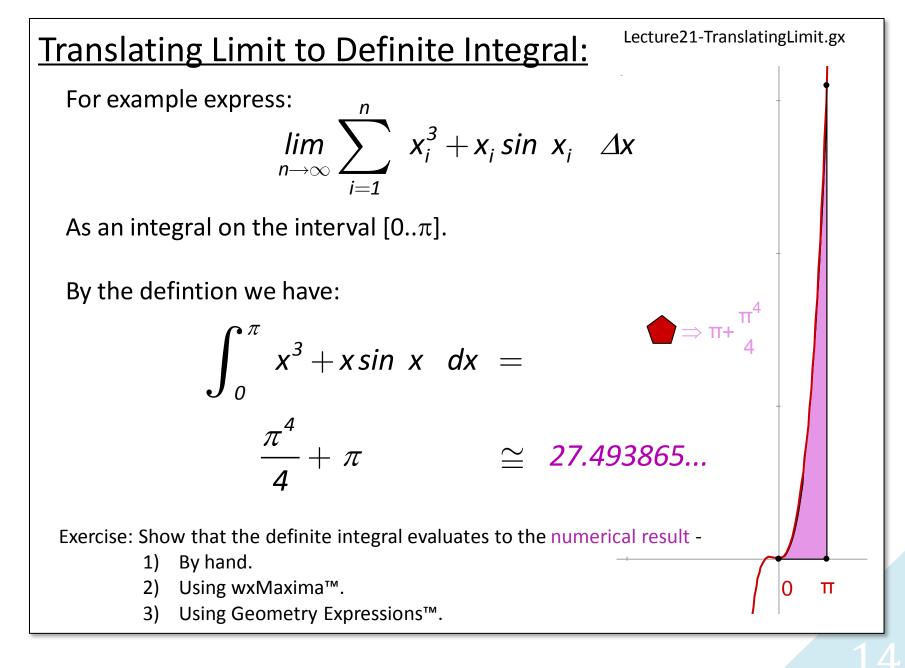
$$\int_{a}^{b} f x \, dx = \lim_{n \to \infty} \sum_{i=1}^{n} f x_{i} \, \Delta x$$

Provided the limit exists.

In this case:

$$\Delta x = \frac{b-a}{n}$$
$$x_i = a + i \Delta x$$

and



Example: Finite Riemann Sum:

For example consider:

$$\sum_{i=1}^{3} x_i^3 - 6x \Delta x$$

We seek the area on the interval [0..3] with $\Delta x = 1$ and $x_i = i$. Writing the terms of the summation we have:

$$x_{1}^{3} - 6x_{1} \Delta x + x_{2}^{3} - 6x_{2} \Delta x + x_{3}^{3} - 6x_{3} \Delta x =$$

$$1^{3} - 6 \cdot 1 \cdot 1 + 2^{3} - 6 \cdot 2 \cdot 1 + 3^{3} - 6 \cdot 3 \cdot 1 =$$

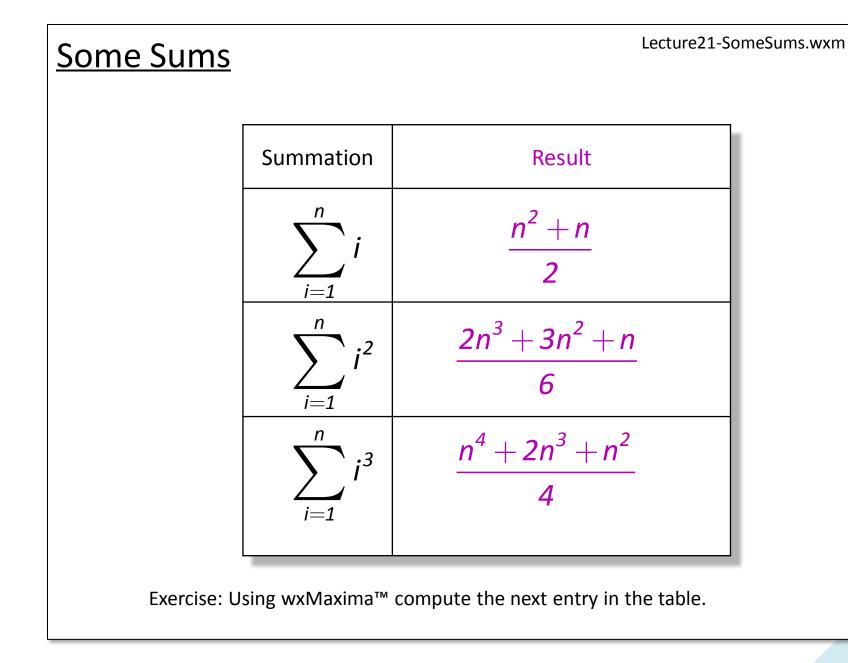
$$1 - 6 + 8 - 12 + 27 - 18 =$$

$$-5 + -4 + 9 = 0$$

Exercise:

- 1) Draw the function using Geometry Expressions[™] and discuss why the Riemann sum is zero.
- 2) Compute the definite integral in wxMaxima[™]. Is zero the correct answer for the area?

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Note 1 on Notation:

The definite integral:

$$\int_{a}^{b} f x \, dx$$

does not depend on x! You get the same answer in each of:

$$\int_a^b f x \, dx = \int_a^b f t \, dt = \int_a^b f s \, ds$$

The result is not a number, but rather a function of the limit variables.

Note 1 on Notation - Example:

Consider the case of a <u>limit variable</u>:

$$\int_{0}^{x} y \, dy = \left. \frac{y^{2}}{2} \right|_{0}^{x} = \left. \frac{x^{2}}{2} - \frac{0^{2}}{2} \right|_{0}^{2} = \frac{x^{2}}{2}$$

Versus a <u>limit constant</u>:

$$\int_{0}^{1} y \, dy = \frac{y^{2}}{2} \Big|_{0}^{1} = \frac{1^{2}}{2} - \frac{0^{2}}{2} = \frac{1}{2}$$

The first expression is a function, the second is a number.

If you think about it, functions can be numbers and vica versa.

Note 2 on Notation:

Some claim that: $\int_{a}^{b} f x \, dx$ is "all one symbol".

Consider functional notation:

integrate f x , x, a, b ;

which has the same meaning!

The latter is a "functional" with four arguments. It is a "functional" because one of the arguments is itself a function.

But any function can be a functional that accepts functions as an argument because we routinely compose functions as in f(g(x)).

So limits, derivatives and integrals are all just functions.

Note 3 on Notation – Improper Integral:

If the limits a or b of the definite integral $\int_a^b f x \, dx$ are $+\infty$ or $-\infty$,

we say the integral is "improper".

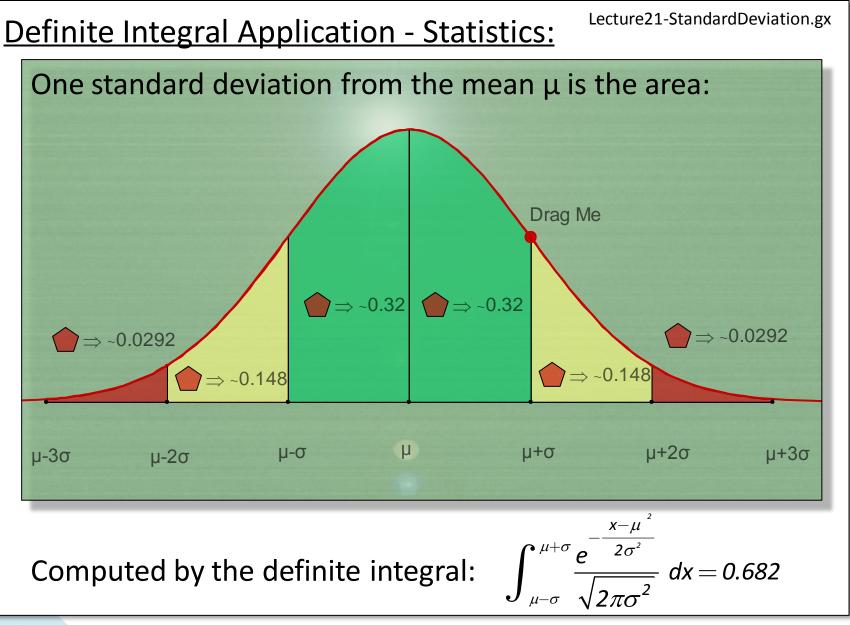
This is something of a misnomer since the limit can still exist. For example, if b is $+\infty$ we write:

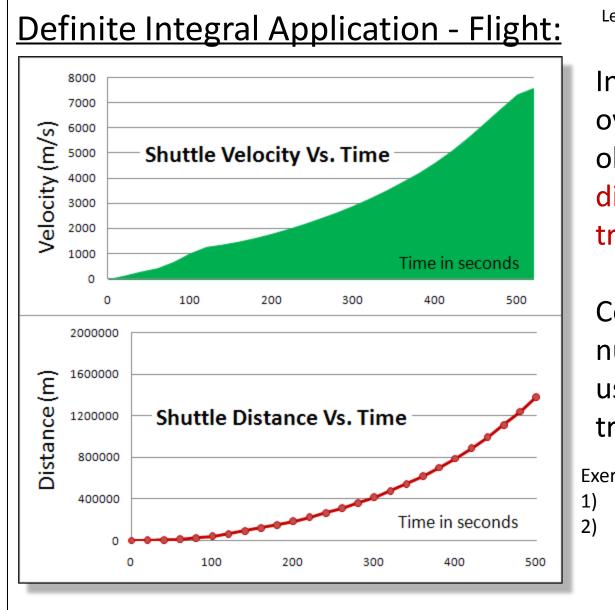
$$\int_{a}^{\infty} f x dx = \lim_{b \to \infty} \int_{a}^{b} f x dx$$

Consider the case of the unnormalized sinc function:

$$\int_{a}^{\infty} \frac{\sin x}{x} dx = \lim_{b \to \infty} \int_{0}^{b} \frac{\sin x}{x} dx = \frac{\pi}{2}$$

Paradoxically, *sinc(x)* cannot be integrated for finite limits!





Lecture21-IntegrateVelocity.xls

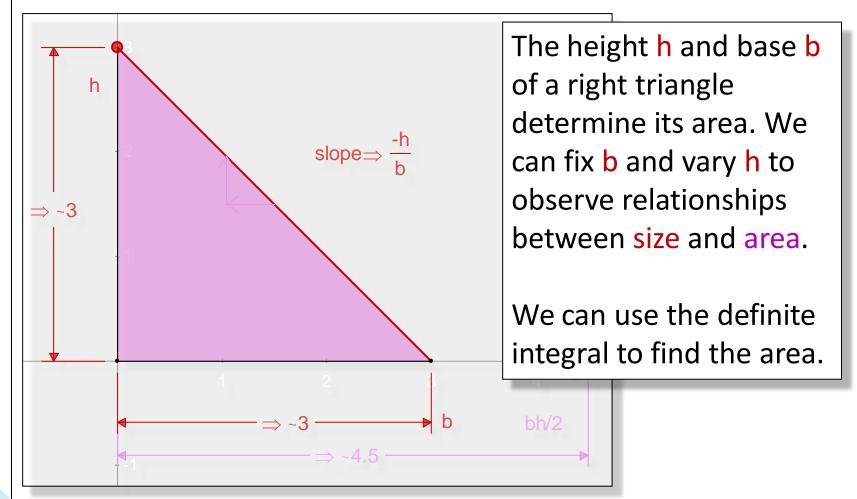
Integrate velocity over time to obtain distance travelled. Computed

numerically using trapezoidal rule.

Exercises:

- 1) Open spreadsheet.
- Use left Riemann sum instead of trapezoidal rule.

Application – Area of a Right Triangle: Lecture21-TriangleArea.gx



Exercise: Drag h and bh/2 to examine size and area relationships.

<u>Definite Integral – Area of a Right Triangle:</u>

The triangle's area can be computed from:

$$A = \int_0^b \left[-\frac{h}{b} x + h \right] dx = \left[-\frac{h}{2b} x^2 + hx \right] \Big|_{x=0}^{x=b} = \frac{bh}{2}$$

The general form for the area under any curve is:

$$A = \int_{a}^{b} f x \, dx$$

Exercise:

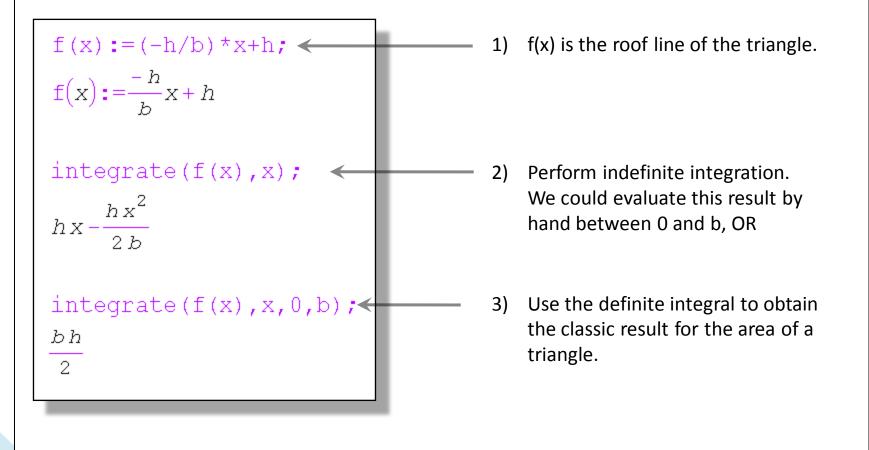
1) Find the area of a rectangle using the integral approach.

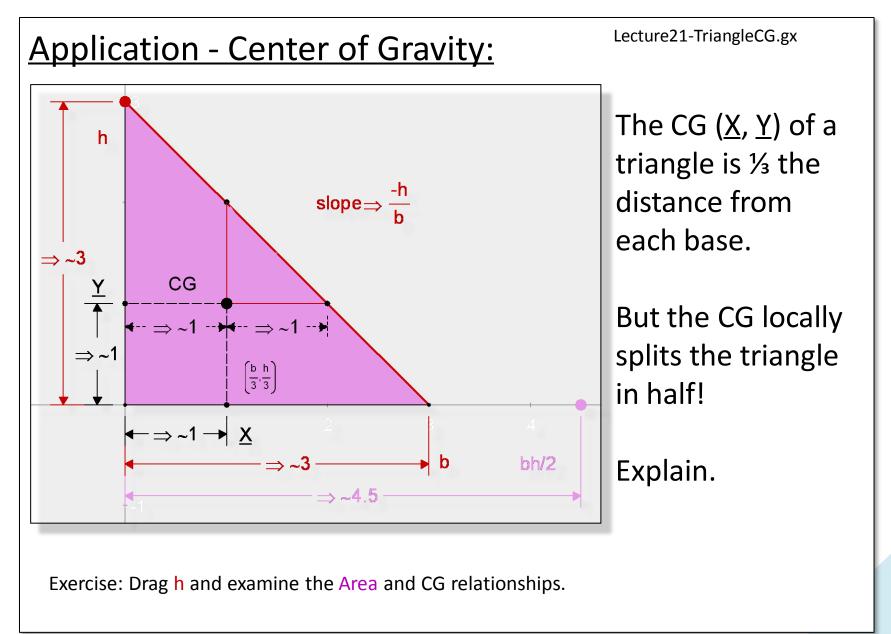
- 2) Find the area of the function y=400 sin(400x) between x = 1 and x = π .
- 3) What is the meaning of negative area?

<u>Definite Integral – Area of a Right Triangle:</u>

Even for simple integrals, symbolic integration reduces errors and speeds discovery:

Lecture21-TriangleArea.wxm





<u>Definite Integral – Center of Gravity:</u>

The x-coordinate of the triangle's CG, \underline{X} , is:

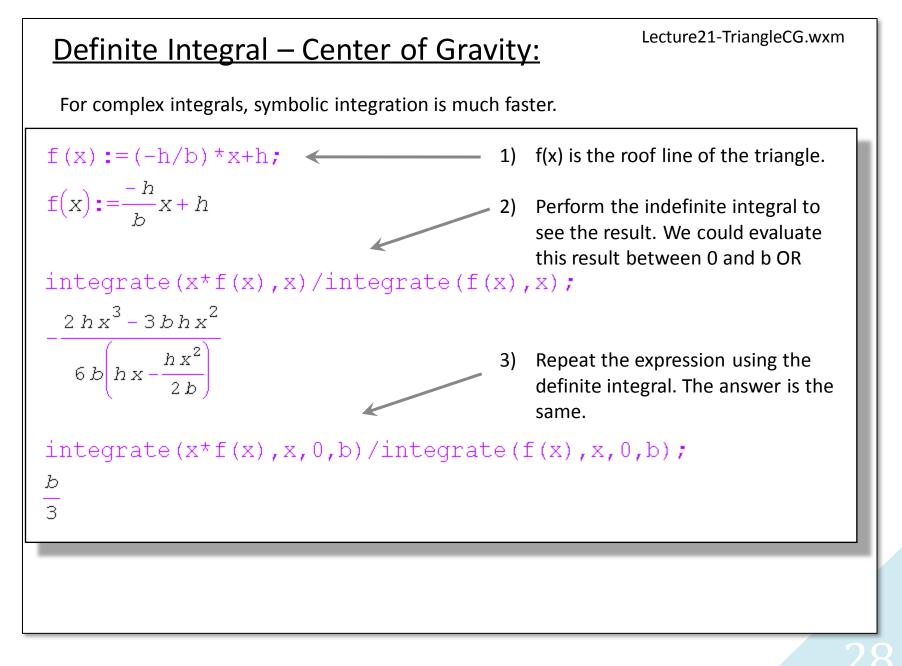
$$\underline{X} = \frac{\int_{0}^{b} x \left[-\frac{h}{b} x + h \right] dx}{\int_{0}^{b} \left[-\frac{h}{b} x + h \right] dx} = \left[-\frac{h}{2b} x^{2} + hx \right] \Big|_{x=0}^{x=\underline{b}} = \frac{b}{3}$$

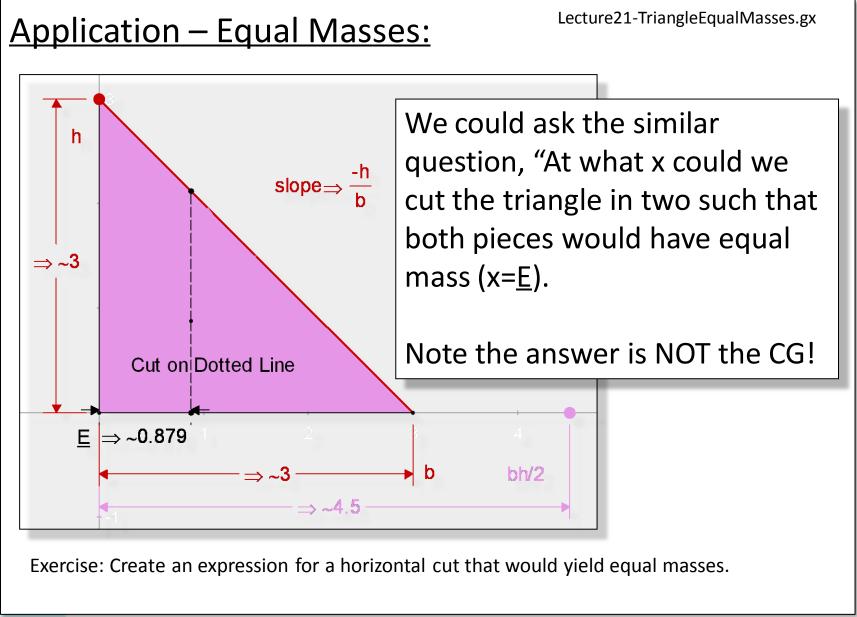
 \underline{X} is the x-axis station at which the triangle would balance on a knife edge. The general form is:

$$\underline{X} = \frac{\int_{a}^{b} x \cdot f x \, dx}{\int_{a}^{b} f x \, dx}$$

Exercise:

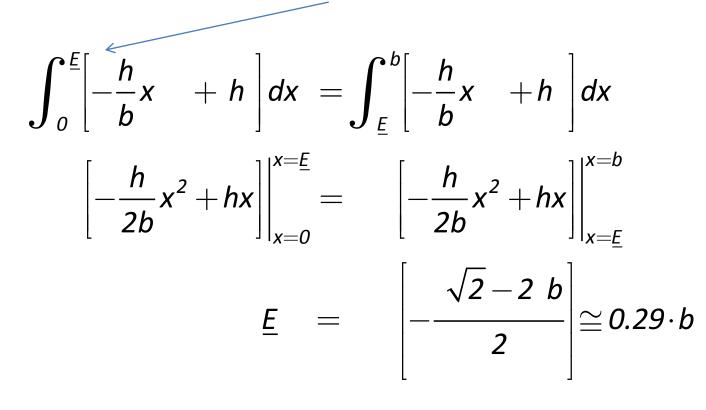
- 1) Show by hand that the next to last step produces the result shown.
- 2) Generate an expression for and compute <u>Y</u>.



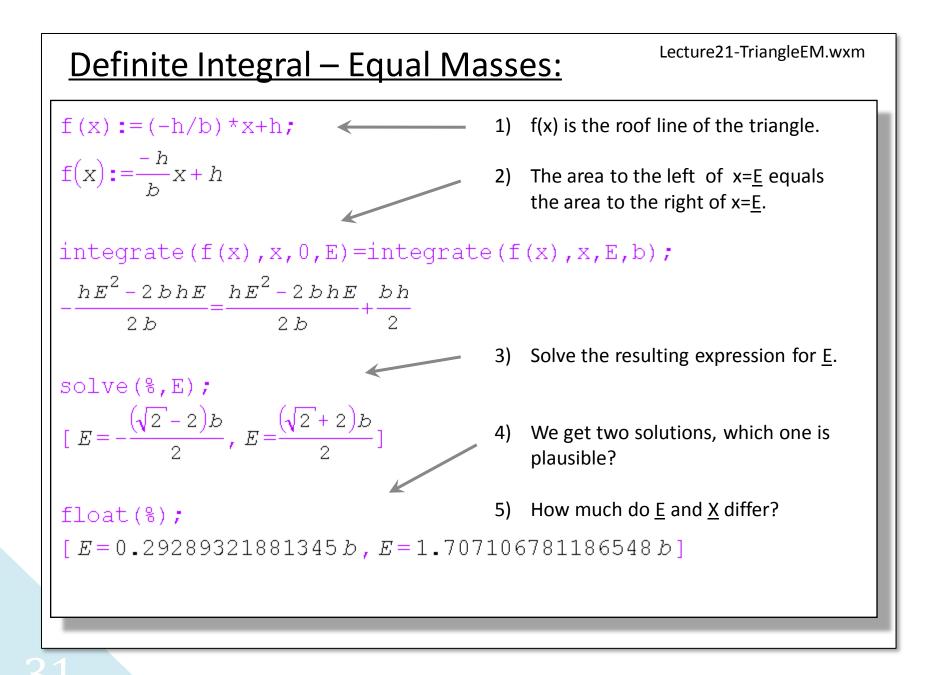


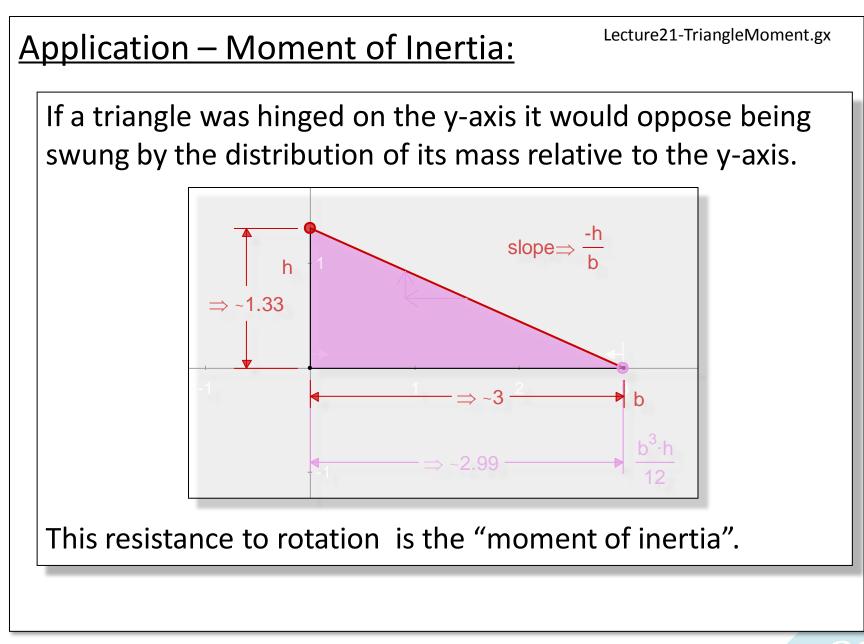
<u>Definite Integral – Equal Masses:</u>

The variable we want to solve for is in <u>upper limit</u> of our integral.



Exercise: Find an algebraic expression for the golden ratio φ . Is there a relationship to <u>E</u>?





<u>Definite Integral – Moment of Inertia:</u>

The triangle's moment of inertia can be computed from:

$$\underline{M} = \int_{0}^{b} x^{2} \left[-\frac{h}{b} x + h \right] dx = \left[-\frac{hx^{4}}{4b} + \frac{hx^{3}}{3} \right] \Big|_{x=0}^{x=b} = \frac{b^{3}h}{12}$$

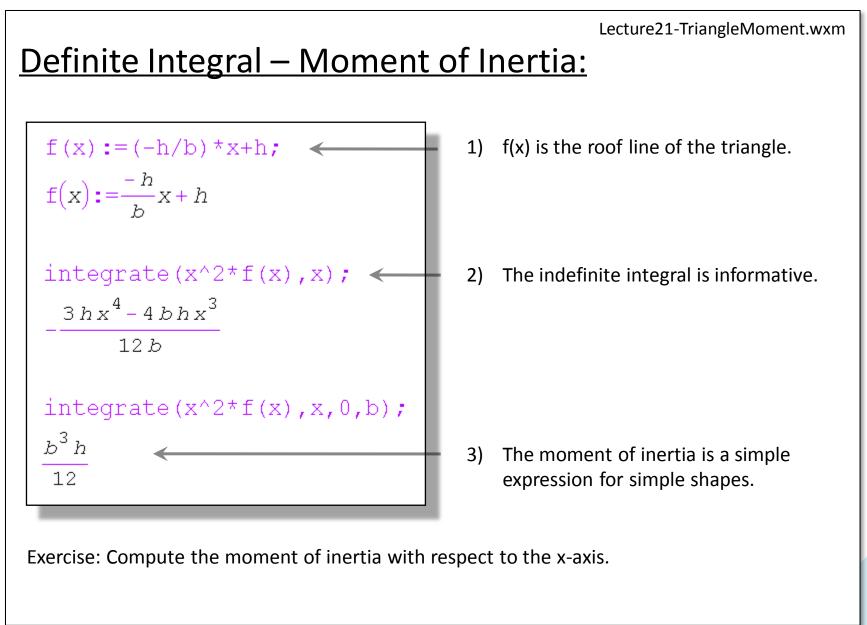
The general form for the moment of inertia about the y-axis for any curve is:

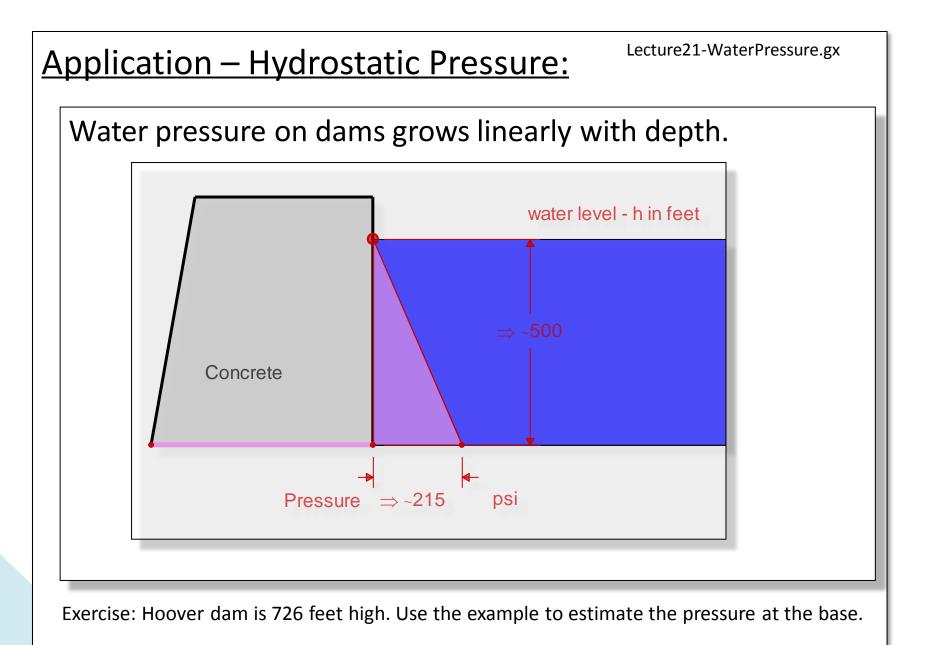
$$\underline{M} = \int_{a}^{b} x^{2} \cdot f x \, dx$$

Exercise:

- 1) Find the moment of a rectangle using the integral approach.
- 2) Find the moment of a semicircle with center (r,0) and radius r.
- 3) Can a moment of inertia be negative?

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<u>Definite Integral – Hydrostatic Pressure:</u>

The water pressure at any depth z is:

$$P(z) = \int_0^z \rho \cdot g \, dy = \rho \cdot g \int_0^z dy = \rho g y \Big|_{y=0}^{y=z} = \rho g z$$

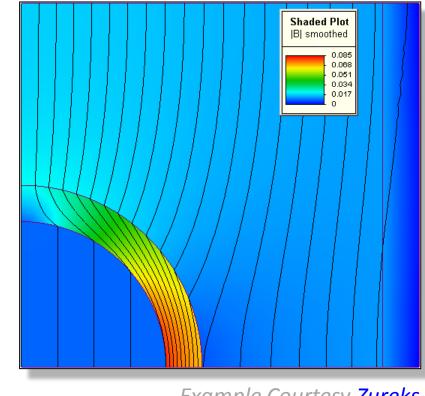
Where ρ is the density of water and g is the acceleration of gravity. Assuming these are constant we can factor them out of the integral to get a formula for pressure of depth z.

Exercise:

- 1) Find the centroid of the pressure triangle in the diagram and compute the value of y at which an equivalent resulting force acts.
- 2) Assuming that the length of the concrete base grows as the integral of the pressure, how does gray concrete area grow with water level, as h^2 or as h^3? Use symbolic calculation of the area of the concrete to justify your answer.
- 3) Assuming the width of the dam is constant, how does concrete cost vary as a function of the water level?

<u>Application – Finite Element Analysis:</u>

Definite Integrals are used to compute stress and strain in critical engineering applications.

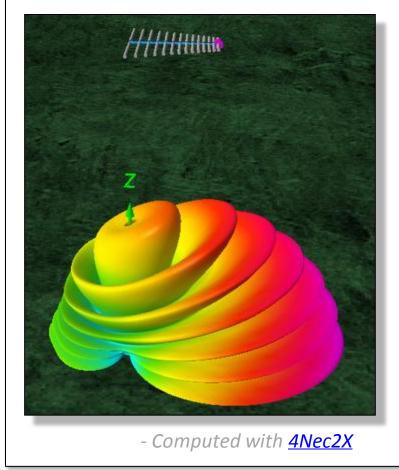


"This is a 2D solution for a cylindrically shaped magnetic shield. The exciting coil with current is shown on the extreme right as a slightly visible vertical rectangle . The lines represent the direction of calculated flux density, the colour is proportional to its magnitude ."

- Example Courtesy Zureks

<u>Application – Electromagnetic Fields:</u>

The propagation of radio frequencies are analyzed by definite integration of Maxwell's equations:

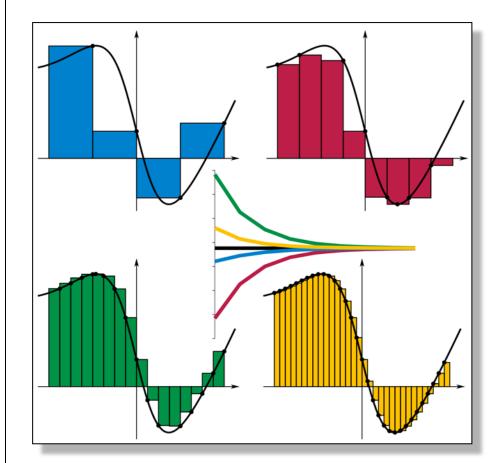


 $\oint \vec{E} \cdot d\vec{A} = \frac{q}{\varepsilon_0}$ Exercise meaning symbols $\oint \vec{B} \cdot d\vec{A} = 0$ Exercise meaning symbols $\oint \vec{E} \cdot d\vec{s} = -\frac{d\Phi_B}{dt}$ $\oint \vec{B} \cdot d\vec{s} = \mu_0 l + \varepsilon_0 \mu_0 \frac{d\Phi_E}{dt}$

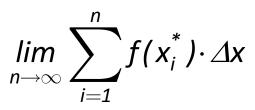
Exercise: Look up the meaning of each of these symbols.

This image shows the antenna gain pattern for a herringbone antenna. The red lobes point in the direction of maximum gain for transmitting and receiving.

Rate of Convergence:

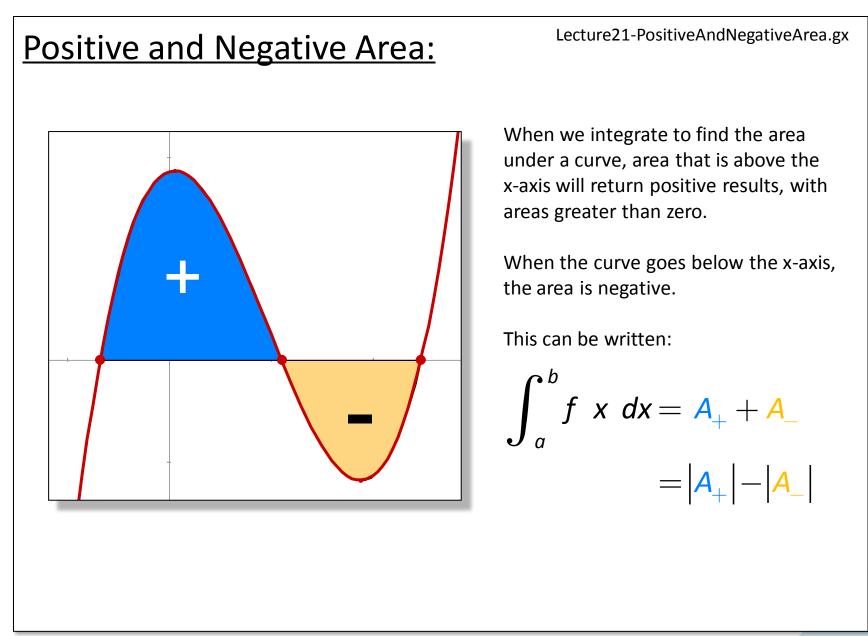


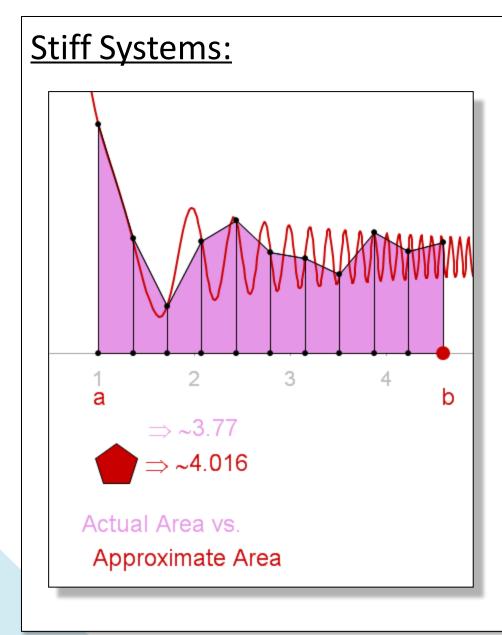
The exact value of an integral can be approximated to any desired degree of accuracy by increasing the value of n in the expression:



The rate at which an approximation approaches the exact value, as n increases, is called the rate of convergence.

Different approximations converge at different rates.





Lecture21-StiffSystems.gx

When a function changes slowly in one interval and rapidly in another we say the function is "stiff".

Stiff functions appear in vibration and impact problems.

William Gear developed integration techniques for stiff systems.

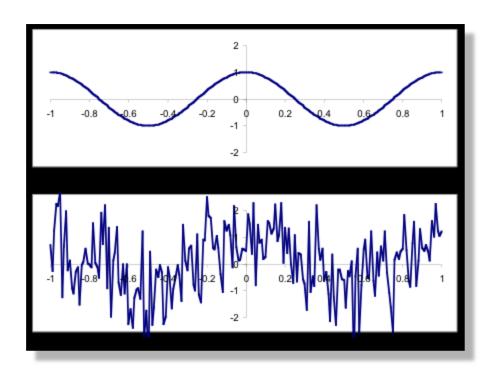
Numerical integration is called "quadrature".

Adaptive Quadrature samples the intervals correctly using recursion.

Exercise:

- 1) Drag b to show the weakness of uniform sampling.
- 2) Which region is undersampled?
- 3) Which is oversampled?

Noisy Systems:



In the presence of noise, an approximate solution can be more accurate than the "exact" solution and often easier to find.

With noisy data integration tends to reduce the error.

Differentiated data with noise is worthless for decision making.

$$\begin{aligned} h[i,j] &:= j \times x \sin(x^{-1}); \\ h_{i,j} &:= j \times \sin(x^{-1}) \\ genmatrix(h,3,3); \\ \begin{bmatrix} x \sin(x) & 2 \times \sin(x) & 3 \times \sin(x) \\ x \sin(x^{2}) & 2 \times \sin(x^{2}) & 3 \times \sin(x^{2}) \\ x \sin(x^{3}) & 2 \times \sin(x^{3}) & 3 \times \sin(x^{3}) \\ \end{bmatrix} \\ & \text{End} \\ integrate(\$, x); \\ \begin{bmatrix} \sin(x) - x \cos(x) & 2(\sin(x) - x \cos(x)) & 3(\sin(x) - x \cos(x)) \\ -\frac{\cos(x^{2})}{2} & -\cos(x^{2}) & -\frac{3\cos(x^{2})}{2} \\ -\frac{\cos(x^{3})dx}{2} & \int 2 x \sin(x^{3})dx & \int 3 x \sin(x^{3})dx \end{bmatrix} \end{aligned}$$